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Nonlinear Systems: Pearson New International Edition EOLSS Publications

Reduced order models, or model reduction, have been used in many technologically advanced areas to ensure the associated complicated mathematical models remain computable. For instance, reduced order models are used to simulate weather forecast models and in the design of very large scale integrated circuits and networked dynamical systems. For linear systems, the model reduction problem has been addressed from several perspectives and a comprehensive theory exists. Although many results and efforts have been made, at present there is no complete theory of model reduction for nonlinear systems or, at least, not as complete as the theory developed for linear systems. This monograph presents, in a uniform and complete fashion, moment matching techniques for nonlinear systems. This includes extensive sections on nonlinear time-delay systems; moment matching from input/output data and the limitations of the characterization of moment based on a signal generator described by differential equations. Each section is enriched with examples and is concluded with extensive bibliographical notes. This monograph provides a comprehensive and accessible introduction into model reduction for researchers and students working on non-linear systems.

Analysis and Design CRC Press

Nonlinear Dynamical Systems and Control presents and develops an extensive treatment of stability analysis and control design of nonlinear dynamical systems, with an emphasis on Lyapunov-based methods. Dynamical system theory lies at the heart of mathematical sciences and engineering. The application of dynamical systems has crossed interdisciplinary boundaries from chemistry to biochemistry to chemical kinetics, from medicine to biology to population genetics, from economics to sociology to psychology, and from physics to mechanics to engineering. The increasingly complex nature of engineering systems requiring feedback control to obtain a desired system behavior also gives rise to dynamical systems. Wassim Haddad and VijaySekhar Chellaboina provide an exhaustive treatment of nonlinear systems theory and control using the highest standards of exposition and rigor. This graduate-level textbook goes well beyond standard treatments by developing Lyapunov stability theory, partial stability, boundedness, input-to-state stability, input-output stability, finite-time stability, semistability, stability of sets and periodic orbits, and stability theorems via vector Lyapunov functions. A complete and thorough treatment of dissipativity theory, absolute stability theory, stability of feedback systems, optimal control, disturbance rejection control, and robust control for nonlinear dynamical systems is also given. This book is an indispensable resource for applied mathematicians, dynamical systems theorists, control theorists, and engineers.

Nonlinear Systems Analysis SIAM

There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications.

Adaptive Control Tutorial John Wiley & Sons

The objective of the EU Nonlinear Control Network Workshop was to bring together scientists who are already active in nonlinear control and young researchers working in this field. This book presents selectively invited contributions from the workshop, some describing state-of-the-art subjects that already have a status of maturity while others propose promising future directions in nonlinear control. Amongst others, following topics of nonlinear and adaptive control are included: adaptive and robust control, applications in physical systems, distributed parameter systems, disturbance attenuation, dynamic feedback, optimal control, sliding mode control, and tracking and motion planning.

An Operator Perspective Prentice Hall

This updated and expanded edition of the bestselling textbook provides a comprehensive introduction to the methods and theory of nonlinear finite element analysis. New material provides a concise introduction to some of the cutting-edge methods that have evolved in recent years in the field of nonlinear finite element modeling, and includes the eXtended finite element method (XFEM), multiresolution continuum theory for multiscale microstructures, and dislocation-density-based crystalline plasticity. Nonlinear Finite Elements for Continua and Structures, Second Edition focuses on the formulation and solution of discrete equations for various classes of problems that are of principal interest in applications to solid and structural mechanics. Topics covered include the discretization by finite elements of continua in one dimension and in multi-dimensions; the formulation of constitutive equations for nonlinear materials and large deformations; procedures for the solution of the discrete equations, including considerations of both numerical and multiscale physical instabilities; and the treatment of structural and contact-impact problems. Key features: Presents a detailed and rigorous treatment of nonlinear solid mechanics and how it can be implemented in finite element analysis Covers many of the material laws used in today's software and research Introduces advanced topics in nonlinear finite element modelling of continua Introduction of multiresolution continuum theory and XFEM Accompanied by a website hosting a solution manual and MATLAB® and FORTRAN code Nonlinear Finite Elements for

Continua and Structures, Second Edition is a must have textbook for graduate students in mechanical engineering, civil engineering, applied mathematics, engineering mechanics, and materials science, and is also an excellent source of information for researchers and practitioners in industry.

Control Systems, Robotics and AutomatioN - Volume XII CRC Press

Provides complete coverage of both the Lyapunov and Input-Output stability theories, in a readable, concise manner. * Supplies an introduction to the popular backstepping approach to nonlinear control design * Gives a thorough discussion of the concept of input-to-state stability * Includes a discussion of the fundamentals of feedback linearization and related results. * Details complete coverage of the fundamentals of dissipative system's theory and its application in the so-called L2gain control problem, for the first time in an introductory level textbook. * Contains a thorough discussion of nonlinear observers, a very important problem, not commonly encountered in textbooks at this level. *An Instructor's Manual presenting detailed solutions to all the problems in the book is available from the Wiley editorial department.

Time-Domain and Frequency-Domain Methods Athena Scientific

Based largely on state space models, this text/reference utilizes fundamental linear algebra and operator techniques to develop classical and modern results in linear systems analysis and control design. It presents stability and performance results for linear systems, provides a geometric perspective on controllability and observability, and develops state space realizations of transfer functions. It also studies stabilizability and detectability, constructs state feedback controllers and asymptotic state estimators, covers the linear quadratic regulator problem in detail, introduces H-infinity control, and presents results on Hamiltonian matrices and Riccati equations.

Analysis, Stability, and Control Springer

At publication, The Control Handbook immediately became the definitive resource that engineers working with modern control systems required.

Among its many accolades, that first edition was cited by the AAP as the Best Engineering Handbook of 1996. Now, 15 years later, William Levine has once again compiled the most comprehensive and authoritative resource on control engineering. He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields. Now expanded from one to three volumes, The Control Handbook, Second Edition organizes cutting-edge contributions from more than 200 leading experts. The third volume, Control System Advanced Methods, includes design and analysis methods for MIMO linear and LTI systems, Kalman filters and observers, hybrid systems, and nonlinear systems. It also covers advanced considerations regarding — Stability Adaptive controls System identification Stochastic control Control of distributed parameter systems Networks and networked controls As with the first edition, the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances. Progressively organized, the first two volumes in the set include: Control System Fundamentals Control System Applications

Pearson Higher Ed

Singular perturbations and time-scale techniques were introduced to control engineering in the late 1960s and have since become common tools for the modeling, analysis, and design of control systems. In this SIAM Classics edition of the 1986 book, the original text is reprinted in its entirety (along with a new preface), providing once again the theoretical foundation for representative control applications. This book continues to be essential in many ways. It lays down the foundation of singular perturbation theory for linear and nonlinear systems, it presents the methodology in a pedagogical way that is not available anywhere else, and it illustrates the theory with many solved examples, including various physical examples and applications. So while new developments may go beyond the topics covered in this book, they are still based on the methodology described here, which continues to be their common starting point.

Nonlinear Finite Elements for Continua and Structures CRC Press

This book explores topics that are central to the field of spacecraft attitude determination and control. The authors provide rigorous theoretical derivations of significant algorithms accompanied by a generous amount of qualitative discussions of the subject matter. The book documents the development of the important concepts and methods in a manner accessible to practicing engineers, graduate-level engineering students and applied mathematicians. It includes detailed examples from actual mission designs to help ease the transition from theory to practice and also provides prototype algorithms that are readily available on the author's website. Subject matter includes both theoretical derivations and practical implementation of spacecraft attitude determination and control systems. It provides detailed derivations for attitude kinematics and dynamics and provides detailed description of the most widely used attitude parameterization, the quaternion. This title also provides a thorough treatise of attitude dynamics including Jacobian elliptical functions. It is the first known book to provide detailed derivations and explanations of state attitude determination and gives readers real-world examples from actual working spacecraft missions. The subject matter is chosen to fill the void of existing textbooks and treatises, especially in state and dynamics attitude determination. MATLAB code of all examples will be provided through an external website.

Nonlinear Systems Pearson

Nonlinear Systems Pearson New International Edition Pearson

A Lyapunov-Based Approach MacMillan Publishing Company

For a first course on nonlinear control that can be taught in one semester This book emerges from the award-winning book, Nonlinear Systems, but has a distinctly different mission and organization. While Nonlinear Systems was intended as a reference and a text on nonlinear system analysis and its application to control, this streamlined book is intended as a text for a first course on nonlinear control. In Nonlinear Control, author Hassan K. Khalil employs a writing style that is intended to make the book accessible to a wider audience without compromising the rigor of the presentation. Teaching and Learning Experience This program will provide a better teaching and learning experience—for you and your students. It will help: Provide an Accessible Approach to Nonlinear Control: This streamlined book is intended as a text for a first course on nonlinear control that can be taught in one semester. Support Learning: Over 250 end-of-chapter exercises give students plenty of opportunities to put theory into action.

Differential Equations SIAM

When M. Vidyasagar wrote the first edition of Nonlinear Systems Analysis, most control theorists considered the subject of nonlinear systems a mystery. Since then, advances in the application of differential geometric methods to nonlinear analysis have matured to a stage where every control theorist needs to possess knowledge of the basic techniques because virtually all physical systems are nonlinear in nature. The second edition, now republished in SIAM's Classics in Applied Mathematics series, provides a rigorous mathematical analysis of the behavior of nonlinear control systems under a variety of situations. It develops nonlinear generalizations of a large number of techniques and methods widely used in linear control theory. The book contains three extensive chapters devoted to the key topics of Lyapunov stability, input-output stability, and the treatment of differential geometric control theory. Audience: this text is designed for use at the graduate level in the area of nonlinear systems and as a resource for professional researchers and practitioners working in areas such as robotics, spacecraft control, motor control, and power systems.

Nonlinear Control World Scientific

For a first-year graduate-level course on nonlinear systems. It may also be used for self-study or reference by engineers and applied mathematicians. The text is written to build the level of mathematical sophistication from chapter to chapter. It has been reorganized into four parts: Basic analysis, Analysis of feedback systems, Advanced analysis, and Nonlinear feedback control.

High-Gain Observers in Nonlinear Feedback Control Prentice Hall

There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications.

Analysis, Stability, and Control Springer Science & Business Media

Designed to meet the needs of a wide audience without sacrificing mathematical depth and rigor, Adaptive Control Tutorial presents the design, analysis, and application of a wide variety of algorithms that can be used to manage dynamical systems with unknown parameters. Its tutorial-style presentation of the fundamental techniques and algorithms in adaptive control make it suitable as a textbook. Adaptive Control Tutorial is designed to serve the needs of three distinct groups of readers: engineers and students interested in learning how to design, simulate, and implement parameter estimators and adaptive control schemes without having to fully understand the analytical and technical proofs; graduate students who, in addition to attaining the aforementioned objectives, also want to understand the analysis of simple schemes and get an idea of the steps involved in more complex proofs; and advanced students and researchers who want to study and understand the details of long and technical proofs with an eye toward pursuing research in adaptive control or related topics. The authors achieve these multiple objectives by enriching the book with examples

demonstrating the design procedures and basic analysis steps and by detailing their proofs in both an appendix and electronically available supplementary material; online examples are also available. A solution manual for instructors can be obtained by contacting SIAM or the authors. Preface; Acknowledgements; List of Acronyms; Chapter 1: Introduction; Chapter 2: Parametric Models; Chapter 3: Parameter Identification: Continuous Time; Chapter 4: Parameter Identification: Discrete Time; Chapter 5: Continuous-Time Model Reference Adaptive Control; Chapter 6: Continuous-Time Adaptive Pole Placement Control; Chapter 7: Adaptive Control for Discrete-Time Systems; Chapter 8: Adaptive Control of Nonlinear Systems; Appendix; Bibliography; Index

Nonlinear Control of Engineering Systems BoD – Books on Demand

For over a quarter of a century, high-gain observers have been used extensively in the design of output feedback control of nonlinear systems. This book presents a clear, unified treatment of the theory of high-gain observers and their use in feedback control. Also provided is a discussion of the separation principle for nonlinear systems; this differs from other separation results in the literature in that recovery of stability as well as performance of state feedback controllers is given. The author provides a detailed discussion of applications of high-gain observers to adaptive control and regulation problems and recent results on the extended high-gain observers. In addition, the author addresses two challenges that face the implementation of high-gain observers: high dimension and measurement noise. Low-power observers are presented for high-dimensional systems. The effect of measurement noise is characterized and techniques to reduce that effect are presented. The book ends with discussion of digital implementation of the observers. Readers will find comprehensive coverage of the main results on high-gain observers; rigorous, self-contained proofs of all results; and numerous examples that illustrate and provide motivation for the results. The book is intended for engineers and applied mathematicians who design or research feedback control systems.

Reinforcement Learning and Optimal Control SIAM

The editors of this book have incorporated contributions from a diverse group of leading researchers in the field of nonlinear systems. To enrich the scope of the content, this book contains a valuable selection of works on fractional differential equations. The book aims to provide an overview of the current knowledge on nonlinear systems and some aspects of fractional calculus. The main subject areas are divided into two theoretical and applied sections. Nonlinear systems are useful for researchers in mathematics, applied mathematics, and physics, as well as graduate students who are studying these systems with reference to their theory and application. This book is also an ideal complement to the specific literature on engineering, biology, health science, and other applied science areas. The opportunity given by IntechOpen to offer this book under the open access system contributes to disseminating the field of nonlinear systems to a wide range of researchers.

NCN4 2001 Oxford University Press, USA

The purpose of this book is to present a self-contained description of the fundamentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teaching at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985.

Applied Nonlinear Control BoD – Books on Demand

For a first-year graduate-level course on nonlinear systems. It may also be used for self-study or reference by engineers and applied mathematicians. The text is written to build the level of mathematical sophistication from chapter to chapter. It has been reorganized into four parts: Basic analysis, Analysis of feedback systems, Advanced analysis, and Nonlinear feedback control.