

Mobile Robotics Mathematics Models And Methods

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COHEN DANIKA

Mobile Robots Navigation Cambridge University Press

This accessible book provides an introduction to the analysis and design of dynamic multiagent networks. Such networks are of great interest in a wide range of areas in science and engineering, including: mobile sensor networks, distributed robotics such as formation flying and swarming, quantum networks, networked economics, biological synchronization, and social networks. Focusing on graph theoretic methods for the analysis and synthesis of dynamic multiagent networks, the book presents a powerful new formalism and set of tools for networked systems. The book's three sections look at foundations, multiagent networks, and networks as systems. The authors give an overview of important ideas from graph theory, followed by a detailed account of the agreement protocol and its various extensions, including the behavior of the protocol over undirected, directed, switching, and random networks. They cover topics such as formation control, coverage, distributed estimation, social networks, and games over networks. And they explore intriguing aspects of viewing networks as systems, by making these networks amenable to control-theoretic analysis and automatic synthesis, by monitoring their dynamic evolution, and by examining higher-order interaction models in terms of simplicial complexes and their applications. The book will interest graduate students working in systems and control, as well as in computer science and robotics. It will be a standard reference for researchers seeking a self-contained account of system-theoretic aspects of multiagent networks and their wide-ranging applications. This book has been adopted as a textbook at the following universities: ? University of Stuttgart, Germany Royal Institute of Technology, Sweden Johannes Kepler University, Austria Georgia Tech, USA University of Washington, USA Ohio University, USA

Probabilistic Robotics Springer Nature

BUILD A CAR ROBOT,SAVE THOU\$AND\$ (and master some of the most sophisticated concepts in robotics) This thoughtful guide gives you complete, illustrated plans and instructions for building a 1:10-scale car robot that would cost thousands of dollars if bought off the shelf. But beyond hours of entertainment and satisfaction spent creating and operating an impressive and fun project, Mobile Robotic Car Design provides serious insight into the science and art of robotics. Written by robotics experts, this book gives you a solid background in electrical and mechanical theory, and the design savvy to conceptualize, enlarge, and build robotics projects of your own. **A WORKING CAR ROBOT—AND AN UNDERSTANDING OF WHAT MAKES IT WORK** In these pages, robot designers Pushkin Kachroo and Patricia Mellodge will help you -- bull; bull;Build an impressive robot vehicle that can regulate its own speed and direction, for a cost of about \$1000. bull;Give your robot car the ability to sense and respond to the environment bull;Experiment with automatic cruise control that alters speed to meet conditions bull;Learn what it takes to build a security robot that can patrol actively or passively bull;Grasp the theory and principles behind robot design and operation bull;Learn what makes servos, sensors, motors, and controls work bull;Examine the source code for the PIC microcontroller and the DSP (digital signal processor) bull;Find free code for the car's printed circuit board at the companion website bull;Get a complete parts list and list of parts suppliers

The Developmental Organization of Robot Behavior MIT Press

Offers a theoretical and practical guide to the communication and navigation of autonomous mobile robots and multi-robot systems This book covers the methods and algorithms for the navigation, motion planning, and control of mobile robots acting individually and in groups. It addresses methods of positioning in global and local coordinates systems, off-line and on-line path-planning, sensing and sensors fusion, algorithms of obstacle avoidance, swarming techniques and cooperative behavior. The book includes ready-to-use algorithms, numerical examples and simulations, which can be directly implemented in both simple and advanced mobile robots, and is accompanied by a website hosting codes, videos, and PowerPoint slides **Autonomous Mobile Robots and Multi-Robot Systems: Motion-Planning, Communication and Swarming** consists of four main parts. The first looks at the models and algorithms of navigation and motion planning in global coordinates systems with complete information about the robot's location and velocity. The second part considers the motion of the robots in the potential field, which is defined by the environmental states of the robot's expectations and knowledge. The robot's motion in the unknown environments and the corresponding tasks of environment mapping using sensed information is covered in the third part. The fourth part deals with the multi-robot systems and swarm dynamics in two and three dimensions. Provides a self-contained, theoretical guide to understanding mobile robot control and navigation Features implementable algorithms, numerical examples, and simulations Includes coverage of models of motion in global and local coordinates systems with and without direct communication between the robots Supplemented by a companion website offering codes, videos, and PowerPoint slides **Autonomous Mobile Robots and Multi-Robot Systems: Motion-Planning, Communication and Swarming** is an excellent tool for researchers, lecturers, senior undergraduate and graduate students, and engineers dealing with mobile robots and related issues.

Mobile Robotics Elsevier

The second edition of a comprehensive introduction to all aspects of mobile robotics, from algorithms to mechanisms. Mobile robots range from the Mars Pathfinder mission's teleoperated Sojourner to the cleaning robots in the Paris Metro. This text offers students and other interested readers an

introduction to the fundamentals of mobile robotics, spanning the mechanical, motor, sensory, perceptual, and cognitive layers the field comprises. The text focuses on mobility itself, offering an overview of the mechanisms that allow a mobile robot to move through a real world environment to perform its tasks, including locomotion, sensing, localization, and motion planning. It synthesizes material from such fields as kinematics, control theory, signal analysis, computer vision, information theory, artificial intelligence, and probability theory. The book presents the techniques and technology that enable mobility in a series of interacting modules. Each chapter treats a different aspect of mobility, as the book moves from low-level to high-level details. It covers all aspects of mobile robotics, including software and hardware design considerations, related technologies, and algorithmic techniques. This second edition has been revised and updated throughout, with 130 pages of new material on such topics as locomotion, perception, localization, and planning and navigation. Problem sets have been added at the end of each chapter. Bringing together all aspects of mobile robotics into one volume, Introduction to Autonomous Mobile Robots can serve as a textbook or a working tool for beginning practitioners. Curriculum developed by Dr. Robert King, Colorado School of Mines, and Dr. James Conrad, University of North Carolina-Charlotte, to accompany the National Instruments LabVIEW Robotics Starter Kit, are available. Included are 13 (6 by Dr. King and 7 by Dr. Conrad) laboratory exercises for using the LabVIEW Robotics Starter Kit to teach mobile robotics concepts.

Introduction to Autonomous Robots IGI Global

The term “mechatronics” was coined in 1969, merging “mecha” from mechanism and “tronics” from electronics, to reflect the original idea at the basis of this discipline, that is, the integration of electrical and mechanical systems into a single device. The spread of this term, and of mechatronics itself, has been growing in the years, including new aspects and disciplines, like control engineering, computer engineering and communication/information engineering. Nowadays mechatronics has a well-defined and fundamental role, in strict relation with robotics. Drawing a sharp border between mechatronics and robotics is impossible, as they share many technologies and objectives. Advanced robots could be defined as mechatronic devices equipped with a “smart brain”, but there are also up-to-date mechatronic devices, used in tight interaction with humans, that are governed by smart architectures (for example, for safety purposes). Aim of this book is to offer a wide overview of new research trends and challenges for both mechatronics and robotics, through the contribution of researchers from different institutions, providing their view on specific subjects they consider as “hot topics” in both fields, with attention to new fields of application, new challenges to the research communities and new technologies available. The reader of this book will enjoy the various contributions, as they have been prepared with actual applications in mind, along a journey from advanced actuators and sensors to human-robot interaction, through robot control, navigation, planning and programming issues. The book presents several state-of-the-art solutions, like multiple-stage actuation to cope with conflicting specification of large motion-spans, ultra-high accuracy, model-based control for high-tech mechatronic systems, modern approaches of software systems engineering to robotics, aand humanoids for human assistance. The reader can also find new techniques in approaching the design of mechatronic systems in some possible industrial and service robotics scenarios, with a particular attention for the interaction between humans and mechanisms.

Distributed Control of Robotic Networks McGraw Hill Professional

A modern and unified treatment of the mechanics, planning, and control of robots, suitable for a first course in robotics.

Modern Robotics Cambridge University Press

Mobile Robotics presents the different tools and methods that enable the design of mobile robots; a discipline booming with the emergence of flying drones, underwater mine-detector robots, robot sailboats and vacuum cleaners. Illustrated with simulations, exercises and examples, this book describes the fundamentals of modeling robots, developing the concepts of actuators, sensors, control and guidance. Three-dimensional simulation tools are also explored, as well as the theoretical basis for the reliable localization of robots within their environment. This revised and updated edition contains additional exercises and a completely new chapter on the Bayes filter, an observer that enhances our understanding of the Kalman filter and facilitates certain proofs.

Mathematical Advances Towards Sustainable Environmental Systems MIT Press

The text discusses fundamental, advanced concepts and applications of robotics and autonomous systems. It further discusses important topics, such as robotics techniques in the manufacturing sector, applications of smart autonomous systems in the healthcare sector, resource optimization in mobile robotics, and smart autonomous transport systems. Features Covers design and application aspects of robotic systems for implementing the concepts of smart manufacturing with reduced human intervention, better accuracy, and enhanced production capacity. Discusses techniques including supervised learning, unsupervised learning, and reinforced learning with real-life examples. Highlights a unified intermodal approach for automated transportation including cars, trucks, ships, and port management. Explains the mechanical design of planetary rovers, and the mechanical design of space manipulators, actuators, and sensors. Presents programming tools and platforms for autonomous robotic systems. The book is primarily written for senior undergraduates, graduate students, and academic researchers in fields including electrical engineering, electronics and communications engineering, computer science and engineering, and automotive engineering. *Introduction to Autonomous Mobile Robots, second edition* Cambridge University Press

This textbook provides a comprehensive, but tutorial, introduction to robotics, computer vision, and control. It is written in a light but informative conversational style, weaving text, figures, mathematics, and lines of code into a cohesive narrative. Over 1600 code examples show how complex problems can be decomposed and solved using just a few simple lines of code. This edition is based on MATLAB® and a number of MathWorks® toolboxes. These provide a set of supported software tools for addressing a broad range of applications in robotics and computer vision. These toolboxes enable the reader to easily bring the algorithmic concepts into practice and work with real, non-trivial, problems. For the beginning student, the book makes the algorithms accessible, the toolbox code can be read to gain understanding, and the examples illustrate how it can be used. The code can also be the starting point for new work, for practitioners, students, or researchers, by writing programs based on toolbox functions. Two co-authors from MathWorks have joined the writing team and bring deep knowledge of these MATLAB toolboxes and workflows.

Numerical Modelling in Robotics Cambridge University Press

Mobile robotics has until now focused on issues like design of controllers and robot hardware. It is now ready to embrace theoretical methods from dynamical systems theory, statistics and system identification to produce a formalized approach based on quantitative analyses and computer models of the interaction between robot, task and environment. This book is a step towards a theoretical understanding of the operation of autonomous mobile robots. It presents cutting-edge research on the application of chaos theory, parametric and non-parametric statistics and dynamical systems theory in this field. Practical examples and case studies show how robot behaviour can be logged, analysed, interpreted and modelled, aiding design of controllers, analysis of agent behaviour and verification of results. As the first book to apply advanced scientific methods to mobile robots it will interest researchers, lecturers and post-graduate students in robotics, artificial intelligence and cognitive science.

State Estimation for Robotics Springer Science & Business Media

This book introduces concepts in mobile, autonomous robotics to 3rd-4th year students in Computer Science or a related discipline. The book covers principles of robot motion, forward and inverse kinematics of robotic arms and simple wheeled platforms, perception, error propagation, localization and simultaneous localization and mapping. The cover picture shows a wind-up toy that is smart enough to not fall off a table just using intelligent mechanism design and illustrate the importance of the mechanism in designing intelligent, autonomous systems. This book is open source, open to contributions, and released under a creative common license.

Artificial Intelligence for Future Generation Robotics John Wiley & Sons

This self-contained introduction to the distributed control of robotic networks offers a distinctive blend of computer science and control theory. The book presents a broad set of tools for understanding coordination algorithms, determining their correctness, and assessing their complexity; and it analyzes various cooperative strategies for tasks such as consensus, rendezvous, connectivity maintenance, deployment, and boundary estimation. The unifying theme is a formal model for robotic networks that explicitly incorporates their communication, sensing, control, and processing capabilities--a model that in turn leads to a common formal language to describe and analyze coordination algorithms. Written for first- and second-year graduate students in control and robotics, the book will also be useful to researchers in control theory, robotics, distributed algorithms, and automata theory. The book provides explanations of the basic concepts and main results, as well as numerous examples and exercises. Self-contained exposition of graph-theoretic concepts, distributed algorithms, and complexity measures for processor networks with fixed interconnection topology and for robotic networks with position-dependent interconnection topology Detailed treatment of averaging and consensus algorithms interpreted as linear iterations on synchronous networks Introduction of geometric notions such as partitions, proximity graphs, and multicenter functions Detailed treatment of motion coordination algorithms for deployment, rendezvous, connectivity maintenance, and boundary estimation

Multimodal Perception and Secure State Estimation for Robotic Mobility Platforms Butterworth-Heinemann

The presence of mobile robots in diverse scenarios is considerably increasing to perform a variety of tasks. Among them, many developments have occurred in the fields of ground, underwater, and flying robotics. Independent of the environment where they move, navigation is a fundamental ability of mobile robots so that they can autonomously complete high-level tasks. This problem can be efficiently addressed through the following actions: First, it is necessary to perceive the environment in which the robot has to move, and extract some relevant information (mapping problem). Second, the robot must be able to estimate its position and orientation within this environment (localization problem). With this information, a trajectory toward the target points must be planned (path planning), and the vehicle must be reactively guided along this trajectory considering either possible changes or interactions with the environment or with the user (control). Given this information, this book introduces current frameworks in these fields (mapping, localization, path planning, and control) and, in general, approaches to any problem related to the navigation of mobile robots, such as odometry, exploration, obstacle avoidance, and simulation.

Trends in Advanced Intelligent Control, Optimization and Automation MIT Press

Mobile robotics is a challenging field with great potential. It covers disciplines including electrical engineering, mechanical engineering, computer science, cognitive science, and social science. It is essential to the design of automated robots, in combination with artificial intelligence, vision, and sensor technologies. Mobile robots are widely used for surveillance, guidance, transportation and entertainment tasks, as well as medical applications. This Special Issue intends to concentrate on recent developments concerning mobile robots and the research surrounding them to enhance studies on the fundamental problems observed in the robots. Various multidisciplinary approaches and integrative contributions including navigation, learning and adaptation, networked system, biologically inspired robots and cognitive methods are welcome contributions to this Special Issue, both from a research and an application perspective.

Wheeled Mobile Robotics John Wiley & Sons

A comprehensive introduction to the mathematical foundations of movement and actuation that apply equally to animals and machines. This textbook offers a computational framework for the sensorimotor stage of development as applied to robotics. Much work in developmental robotics is based on ad hoc examples, without a full computational basis. This book's comprehensive and complete treatment fills the gap, drawing on the principal mechanisms of development in the first year of life to introduce what is essentially an operating system for developing robots. The goal is to apply principles of development to robot systems that not only achieve new levels of performance but also provide evidence for scientific theories of human development.

Bio-inspired Algorithms for Engineering MDPI

Introduction to Mobile Robot Control provides a complete and concise study of modeling, control, and navigation methods for wheeled non-holonomic and omnidirectional mobile robots and manipulators. The book begins with a study of mobile robot drives and corresponding kinematic and dynamic models, and discusses the sensors used in mobile robotics. It then examines a variety of model-based, model-free, and vision-based controllers with unified proof of their stabilization and tracking performance, also addressing the problems of path, motion, and task planning, along with localization and mapping topics. The book provides a host of experimental results, a conceptual overview of systemic and software mobile robot control architectures, and a tour of the use of wheeled mobile robots and manipulators in industry and society. Introduction to Mobile Robot Control is an essential reference, and is also a textbook suitable as a supplement for many university robotics courses. It is accessible to all and can be used as a reference for professionals and researchers in the mobile robotics field. - Clearly and authoritatively presents mobile robot concepts - Richly illustrated throughout with figures and examples - Key concepts demonstrated with a host of experimental and simulation examples - No prior knowledge of the subject is required; each chapter commences with an introduction and background

Intelligent Robotics and Applications MDPI

Wheeled Mobile Robotics: From Fundamentals Towards Autonomous Systems covers the main topics from the wide area of mobile robotics, explaining all applied theory and application. The book gives the reader a good foundation, enabling them to continue to more advanced topics. Several examples are included for better understanding, many of them accompanied by short MATLAB® script code making it easy to reuse in practical work. The book includes several examples of discussed methods and projects for wheeled mobile robots and some advanced methods for their control and localization. It is an ideal resource for those seeking an understanding of robotics, mechanics, and control, and for engineers and researchers in industrial and other specialized research institutions in the field of wheeled mobile robotics. Beginners with basic math knowledge will benefit from the examples, and engineers with an understanding of basic system theory and control will find it easy to follow the more demanding fundamental parts and advanced methods explained. - Offers comprehensive coverage of the essentials of the field that are suitable for both academics and practitioners - Includes several examples of the application of algorithms in simulations and real laboratory projects - Presents foundation in mobile robotics theory before continuing with more advanced topics - Self-sufficient to beginner readers, covering all important topics in the mobile robotics field - Contains specific topics on modeling, control, sensing, path planning, localization, design architectures, and multi-agent systems

Odour Detection by Mobile Robots Springer Science & Business Media

An introduction to the techniques and algorithms of the newest field in robotics. Probabilistic robotics is a new and growing area in robotics, concerned with perception and control in the face of uncertainty. Building on the field of mathematical statistics, probabilistic robotics endows robots with a new level of robustness in real-world situations. This book introduces the reader to a wealth of techniques and algorithms in the field. All algorithms are based on a single overarching mathematical foundation. Each chapter provides example implementations in pseudo code, detailed mathematical derivations, discussions from a practitioner's perspective, and extensive lists of exercises and class projects. The book's Web site, www.probablistic-robotics.org, has additional material. The book is relevant for anyone involved in robotic software development and scientific research. It will also be of interest to applied statisticians and engineers dealing with real-world sensor data.

Methodologies and Use Cases on Extended Reality for Training and Education Springer

Mobile Robotics offers comprehensive coverage of the essentials of the field suitable for both students and practitioners. Adapted from Alonzo Kelly's graduate and undergraduate courses, the content of the book reflects current approaches to developing effective mobile robots. Professor Kelly adapts principles and techniques from the fields of mathematics, physics and numerical methods to present a consistent framework in a notation that facilitates learning and highlights relationships between topics. This text was developed specifically to be accessible to senior level undergraduates in engineering and computer science, and includes supporting exercises to reinforce the lessons of each section. Practitioners will value Kelly's perspectives on practical applications of these principles. Complex subjects are reduced to implementable algorithms extracted from real systems wherever possible, to enhance the real-world relevance of the text.

Computational Principles of Mobile Robotics OmniaScience

This book features selected papers presented at the 15th International Conference on Electromechanics and Robotics "Zavalishin's Readings" - ER(ZR) 2020, held in Ufa, Russia, on 15-18 April 2020. The contributions, written by professionals, researchers and students, cover topics in the field of automatic control systems, electromechanics, electric power engineering and electrical engineering, mechatronics, robotics, automation and vibration technologies. The Zavalishin's Readings conference was established as a tribute to the memory of Dmitry Aleksandrovich Zavalishin (1900-1968) - a Russian scientist, corresponding member of the USSR Academy of Sciences and founder of the school of valve energy converters based on electric machines and valve converters energy. The first conference was organized by the Institute of Innovative Technologies in Electromechanics and Robotics at the Saint Petersburg State University of Aerospace Instrumentation in 2006.