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Emerging Trends in Sliding Mode Control Springer Nature

A principal objective of control engineering is to design control systems which are robust with respect to external disturbances and modelling uncertainty. This objective may be well achieved using the sliding mode technique - which is the main subject of this monograph. More precisely, "Time-Varying Sliding Modes for Second and Third Order Systems" focuses on only one, but very important aspect of the sliding mode system design, i.e. the problem of the sliding plane selection. In this self-contained monograph, the main notions and concepts used in the field of variable structure systems and sliding mode control are presented before in the main part the issue of the switching surface design is discussed. This is done by considering two standard plants, which are very often encountered in the control engineering practice: the second and the third order nonlinear and possibly time-varying systems.

Concept, Theory and Implementation Springer
Sliding Mode Control and Observation Springer Science & Business Media

Lecture Notes in Real-Time Intelligent Systems Springer

Featuring contributions from leading experts, the Road and Off-Road Vehicle System Dynamics Handbook provides comprehensive, authoritative coverage of all the major issues involved in road vehicle dynamic behavior. While the focus is on automobiles, this book also highlights motorcycles, heavy commercial vehicles, and off-road vehicles. The authors
Intelligent Manufacturing & Mechatronics Springer

The book is devoted to systems with discontinuous control. The study of discontinuous dynamic systems is a multifacet problem which embraces mathematical, control theoretic and application aspects. Times and again, this problem has been approached by mathematicians, physicists and engineers, each profession treating it from its own positions. Interestingly, the results obtained by specialists in different disciplines have almost always had a significant effect upon the development of the control theory. It suffices to mention works on the theory of oscillations of discontinuous nonlinear systems, mathematical studies in ordinary differential equations with discontinuous righthand parts or variational problems in nonclassic statements. The unremitting interest to discontinuous control systems enhanced by their effective application to solution of problems most diverse in their physical nature and functional purpose is, in the author's opinion, a cogent argument in favour of the importance of this area of studies. It seems a useful effort to consider, from a control theoretic viewpoint, the mathematical and application aspects of the theory of discontinuous dynamic systems and determine their place within the scope of the present-day control theory. The first attempt was made by the author in 1975-1976 in his course on "The Theory of Discontinuous Dynamic Systems" and "The Theory of Variable Structure Systems" read to post-graduates at the

University of Illinois, USA, and then presented in 1978-1979 at the seminars held in the Laboratory of Systems with Discontinuous Control at the Institute of Control Sciences in Moscow.

Variable-Structure Systems and Sliding-Mode Control Sliding Mode Control and Observation

This book presents the proceedings of SympoSIMM 2018, the 1st edition of the Symposium on Intelligent Manufacturing and Mechatronics. With the theme of "Strengthening Innovations Towards Industry 4.0", the book comprises the studies towards the particularity of Industry 4.0's current trends. It is divided into five parts covering various scopes of manufacturing engineering and mechatronics stream, namely Intelligent Manufacturing, Robotics, Artificial Intelligence, Instrumentation, and Modelling and Simulation. It is hoped that this book will benefit the readers in embracing the new era of Industrial Revolution 4.0.

The Delta-Sigma Modulation Approach BoD - Books on Demand
This volume offers a general view of recent conceptual developments of Soft Computing (SC). It presents successful new applications of SC to real-world problems leading to better performance than "traditional" methods. The edited volume covers a wide spectrum of applications including areas such as: robotic dynamic systems, non-linear plants, manufacturing systems, and time series prediction.

Proceedings of the 6th International Conference on Computer Science, Applied Mathematics and Applications, ICCSAMA 2019 Academic Press

The book presents the newest results of the major world research groups working in the area of Variable Structure Systems and Sliding Mode Control (VSS/SMC). The research activity of these groups is coordinated by the IEEE Technical Committee on Variable Structure Systems (VSS) and Sliding Modes (SM). The presented results include the reports of the research groups collaborating in a framework of the Unión European Union - México project of Fondo de Cooperación Internacional en Ciencia y Tecnología (FONCICyT) 93302 titled "Automatization and Monitoring of Energy Production Processes via Sliding Mode Control". The book starts with the overview of the sliding mode control concepts and algorithms that were developed and discussed in the last two decades. The research papers are combined in three sections: Part I: VSS and SM Algorithms and their Analysis Part II: SMC Design Part III: Applications of VSS and SMC. The book will be of interests of engineers, researchers and graduate students working in the area of the control systems design. Novel mathematical theories and engineering concepts of control systems are rigorously discussed and supported by numerous applications to practical tasks.

Advanced Computational Methods for Knowledge Engineering European Control Association

Apply Sliding Mode Theory to Solve Control Problems Interest in SMC has grown rapidly since the first edition of this book was published. This second edition includes new results that have been achieved in SMC throughout the past decade relating to both control design methodology and applications. In that time, Sliding Mode Control (SMC) has continued to gain increasing

importance as a universal design tool for the robust control of linear and nonlinear electro-mechanical systems. Its strengths result from its simple, flexible, and highly cost-effective approach to design and implementation. Most importantly, SMC promotes inherent order reduction and allows for the direct incorporation of robustness against system uncertainties and disturbances. These qualities lead to dramatic improvements in stability and help enable the design of high-performance control systems at low cost. Written by three of the most respected experts in the field, including one of its originators, this updated edition of *Sliding Mode Control in Electro-Mechanical Systems* reflects developments in the field over the past decade. It builds on the solid fundamentals presented in the first edition to promote a deeper understanding of the conventional SMC methodology, and it examines new design principles in order to broaden the application potential of SMC. SMC is particularly useful for the design of electromechanical systems because of its discontinuous structure. In fact, where the hardware of many electromechanical systems (such as electric motors) prescribes discontinuous inputs, SMC becomes the natural choice for direct implementation. This book provides a unique combination of theory, implementation issues, and examples of real-life applications reflective of the authors' own industry-leading work in the development of robotics, automobiles, and other technological breakthroughs.

Nonlinear Stochastic Systems with Network-Induced Phenomena Springer

This book contains 38 papers authored by both scientists and practitioners focused on an interdisciplinary approach to the development of cyber-physical systems. Recently our civilization has been facing one of the most severe challenges in modern history. The COVID-19 pandemic devastated the global economy and significantly disrupted numerous areas of economic activity. Only radical increase of efficiency and versatility of industrial production, with further limitation of human involvement, paralleled by the decrease of environmental burden, will enable us to cope with such challenges. We hope that the presented book provides input to the solution of at least some problems brought about by this challenge. This approach relies on the development of measuring techniques, robotic and mechatronic systems, industrial automation, numerical modeling and simulation as well as application of artificial intelligence techniques required by the transformation leading to Industry 4.0.

European Control Conference 1995 Springer

The main objective of this monograph is to present a broad range of well worked out, recent application studies as well as theoretical contributions in the field of sliding mode control system analysis and design. The contributions presented here include new theoretical developments as well as successful applications of variable structure controllers primarily in the field of power electronics, electric drives and motion steering systems. They enrich the current state of the art, and motivate and encourage new ideas and solutions in the sliding mode control area.

Automation and Robotics Springer

This proceedings book contains 37 papers selected from the submissions to the 6th International Conference on Computer Science, Applied Mathematics and Applications (ICCSAMA 2019), which was held on 19–20 December, 2019, in Hanoi, Vietnam. The book covers theoretical and algorithmic as well as practical issues connected with several domains of Applied Mathematics and Computer Science, especially Optimization and Data Science. The content is divided into four major sections: Nonconvex Optimization, DC Programming & DCA, and Applications; Data

Mining and Data Processing; Machine Learning Methods and Applications; and Knowledge Information and Engineering Systems. Researchers and practitioners in related areas will find a wealth of inspiring ideas and useful tools & techniques for their own work.

Proceedings of the 2nd Symposium on Intelligent Manufacturing and Mechatronics – SympoSIMM 2019, 8 July 2019, Melaka, Malaysia Springer Nature

This book presents the proceedings of SympoSIMM 2019, the 2nd edition of the Symposium on Intelligent Manufacturing and Mechatronics. Focusing on “Strengthening Innovations Towards Industry 4.0”, the book presents studies on the details of Industry 4.0’s current trends. Divided into five parts covering various areas of manufacturing engineering and mechatronics stream, namely, artificial intelligence, instrumentation and controls, intelligent manufacturing, modelling and simulation, and robotics., the book is a valuable resource for readers wishing to embrace the new era of Industry 4.0.

Univelt Incorporated

This monograph introduces methods for handling filtering and control problems in nonlinear stochastic systems arising from network-induced phenomena consequent on limited communication capacity. Such phenomena include communication delay, packet dropout, signal quantization or saturation, randomly occurring nonlinearities and randomly occurring uncertainties. The text is self-contained, beginning with an introduction to nonlinear stochastic systems, network-induced phenomena and filtering and control, moving through a collection of the latest research results which focuses on the three aspects of: · the state-of-the-art of nonlinear filtering and control; · recent advances in recursive filtering and sliding mode control; and · their potential for application in networked control systems, and concluding with some ideas for future research work. New concepts such as the randomly occurring uncertainty and the probability-constrained performance index are proposed to make the network models as realistic as possible. The power of combinations of such recent tools as the completing-the-square and sums-of-squares techniques, Hamilton–Jacobi–Isaacs matrix inequalities, difference linear matrix inequalities and parameter-dependent matrix inequalities is exploited in treating the mathematical and computational challenges arising from nonlinearity and stochasticity. *Nonlinear Stochastic Systems with Network-Induced Phenomena* establishes a unified framework of control and filtering which will be of value to academic researchers in bringing structure to problems associated with an important class of networked system and offering new means of solving them. The significance of the new concepts, models and methods presented for practical control engineering and signal processing will also make it a valuable reference for engineers dealing with nonlinear control and filtering problems.

Model Predictive Control for AC Motors Springer Science & Business Media

This book provides new insight on the problem of closed-loop performance and oscillations in discontinuous control systems, covering the class of systems that do not necessarily have low-pass filtering properties. The author provides a practical, yet rigorous and exact approach to analysis and design of discontinuous control systems via application of a novel frequency-domain tool: the locus of a perturbed relay system. Presented are a number of practical examples applying the theory to analysis and design of discontinuous control systems from various branches of engineering, including electro-mechanical systems, process control, and electronics. *Discontinuous Control Systems* is intended for readers who have knowledge of linear control theory and will be of interest to

graduate students, researchers, and practicing engineers involved in systems analysis and design.

Select Proceedings of SGESC 2021 Springer

This unique book fulfils the definite need for an accessible book on variable structure systems and also provides the very latest results in research on this topic. Divided into three parts - basics of sliding mode control, new trends in sliding mode control, and applications of sliding mode control - the book contains many numerical design examples, so that readers can quickly understand the design methodologies and their applications to practical problems. Primarily aimed at students and researchers in the field, the book will also be useful for practising control engineers.

Discontinuous Control Systems CRC Press

Due to its abilities to compensate disturbances and uncertainties, disturbance observer based control (DOBC) is regarded as one of the most promising approaches for disturbance-attenuation. One of the first books on DOBC, *Disturbance Observer Based Control: Methods and Applications* presents novel theory results as well as best practices for applica

Sliding Mode Control and Observation Springer Science & Business Media

This book presents recent advanced techniques in sliding mode control and observer design for industrial power systems, focusing on their applications in polymer electrolyte membrane fuel cells and power converters. Readers will find not only valuable new fault detection and isolation techniques based on sliding mode control and observers, but also a number of robust control and estimation methodologies combined with fuzzy neural networks and extended state observer methods. The book also provides necessary experimental and simulation examples for proton exchange membrane fuel cell systems and power converter systems. Given its scope, it offers a valuable resource for undergraduate and graduate students, academics, scientists and engineers who are working in the field.

Sliding Mode Control Methodology in the Applications of Industrial Power Systems Springer

Currently, the modelling and control of mechatronic and robotic systems is an open and challenging field of investigation in both

industry and academia. The book encompasses the kinematic and dynamic modelling, analysis, design, and control of mechatronic and robotic systems, with the scope of improving their performance, as well as simulating and testing novel devices and control architectures. A broad range of disciplines and topics are included, such as robotic manipulation, mobile systems, cable-driven robots, wearable and rehabilitation devices, variable stiffness safety-oriented mechanisms, optimization of robot performance, and energy-saving systems. Modelling and Control of Mechatronic and Robotic Systems Birkhäuser

This book focuses on the development and methodologies of trajectory control of differential-drive wheeled nonholonomic mobile robots. The methodologies are based on kinematic models (posture and configuration) and dynamic models, both subject to uncertainties and/or disturbances. The control designs are developed in rectangular coordinates obtained from the first-order sliding mode control in combination with the use of soft computing techniques, such as fuzzy logic and artificial neural networks. Control laws, as well as online learning and adaptation laws, are obtained using the stability analysis for both the developed kinematic and dynamic controllers, based on Lyapunov's stability theory. An extension to the formation control with multiple differential-drive wheeled nonholonomic mobile robots in trajectory tracking tasks is also provided. Results of simulations and experiments are presented to verify the effectiveness of the proposed control strategies for trajectory tracking situations, considering the parameters of an industrial and a research differential-drive wheeled nonholonomic mobile robot, the PowerBot. Supplementary materials such as source codes and scripts for simulation and visualization of results are made available with the book.

Theory and Application Springer

This edited monograph contains research contributions on a wide range of topics such as stochastic control systems, adaptive control, sliding mode control and parameter identification methods. The book also covers applications of robust and adaptive control to chemical and biotechnological systems. This collection of papers commemorates the 70th birthday of Dr. Alexander S. Poznyak.